



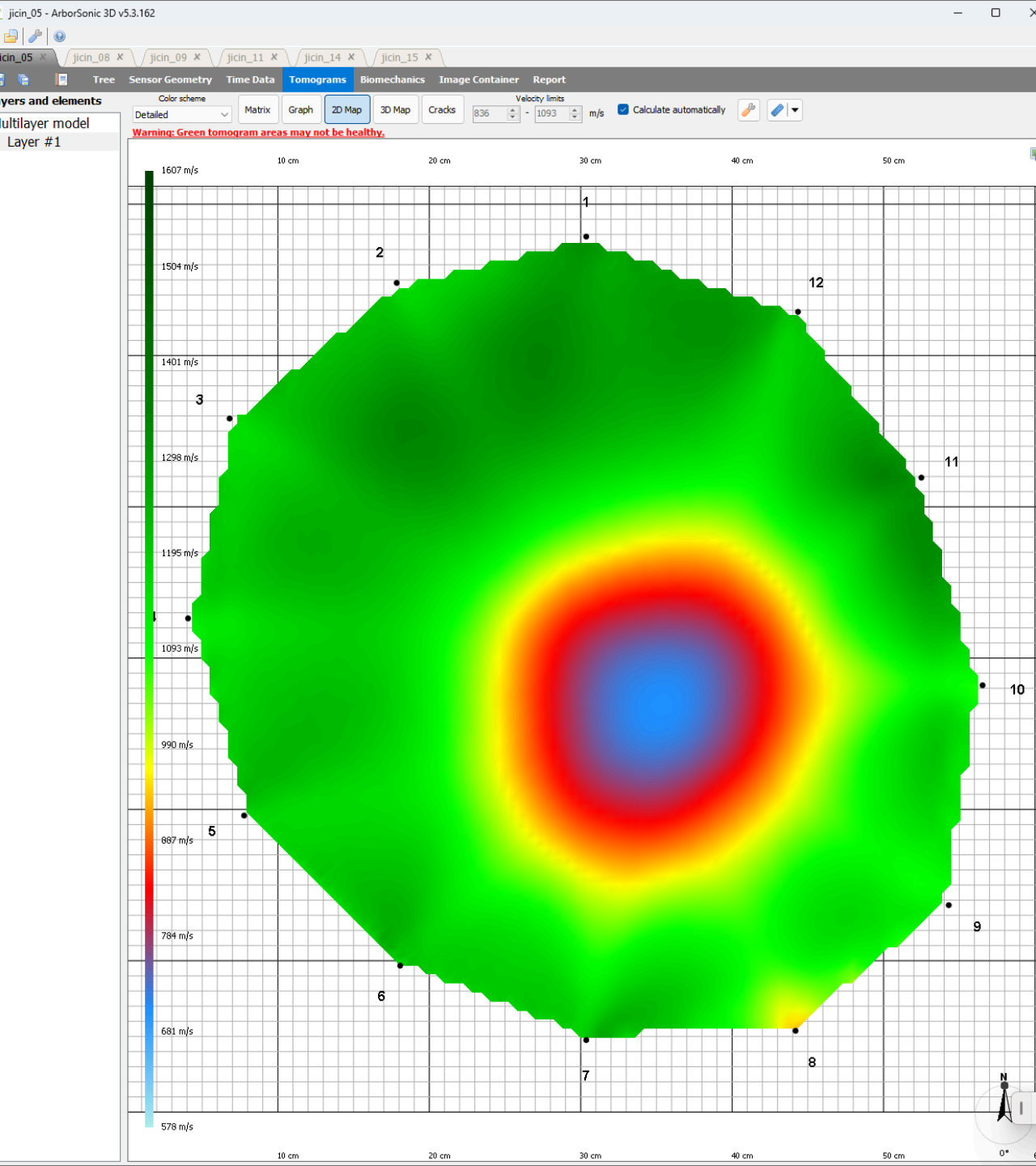
When acoustic tomography meets resistograph

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Content of the talk

- Tomograph and resistograph: strengths and limitations
- Combined approach: a Python library for simultaneous interpretation
- Vibe coding (ChatGPT)
- Code containerization (Docker)

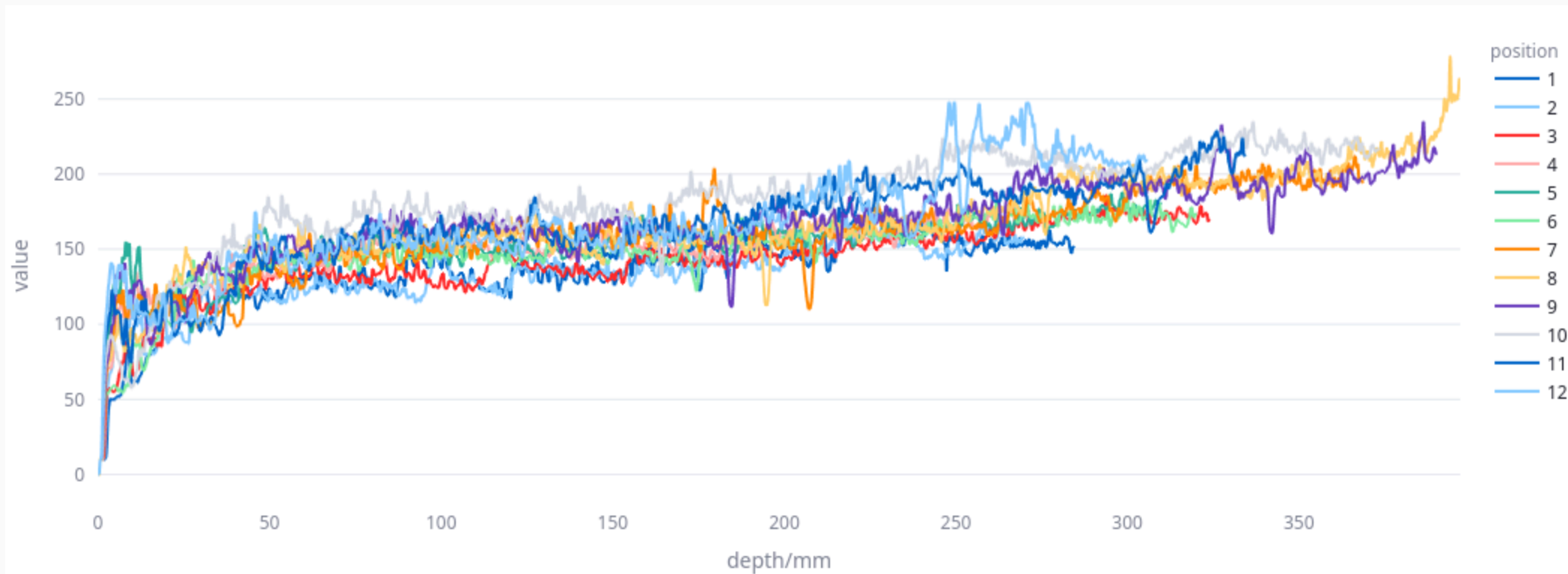


Acoustic tomograph

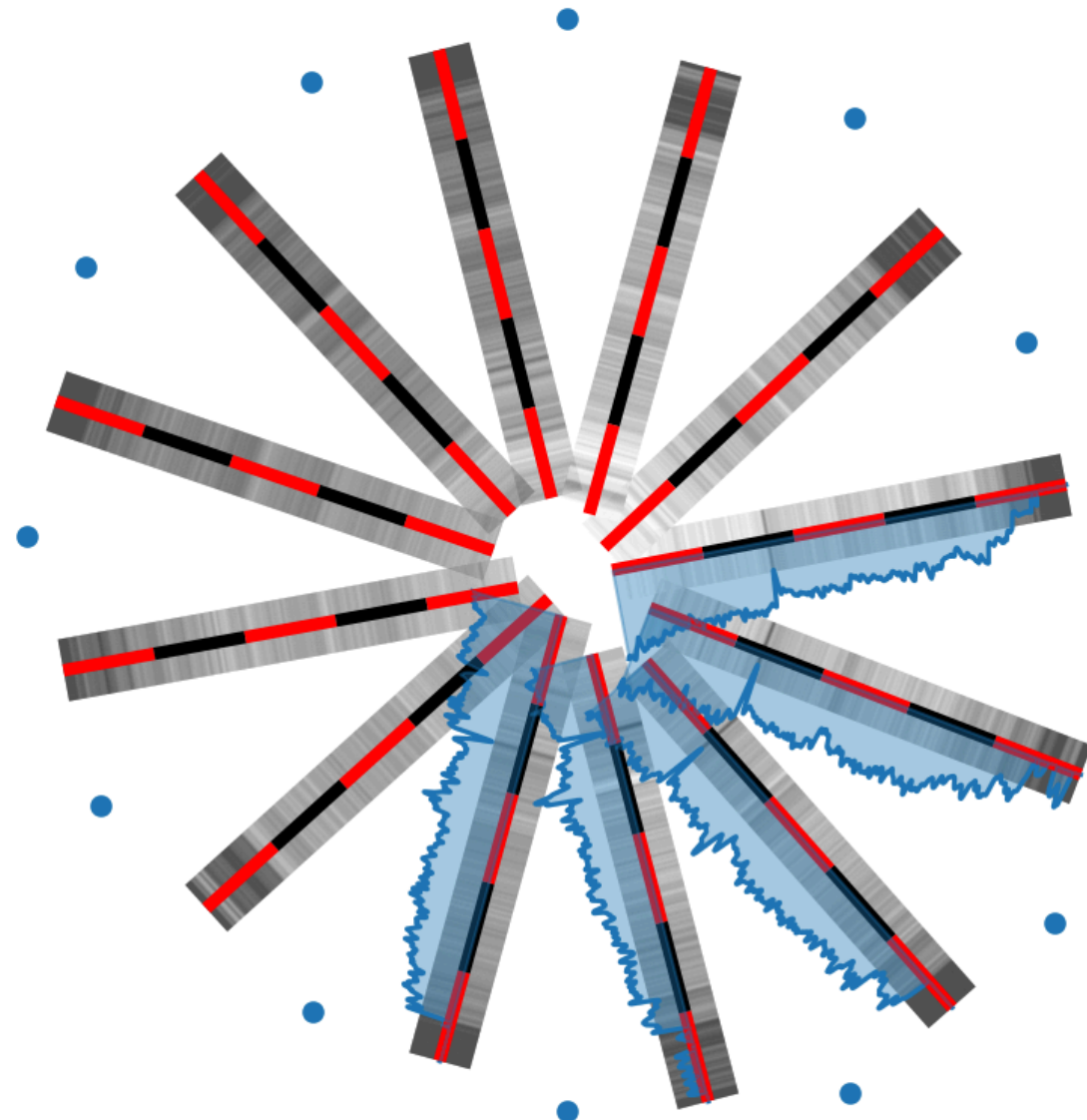
- Tool for fast stem inspection
 - Provides **global information** across the whole cross section
 - Green part - high sound speed value - sound wood
 - Shows size and shape of internal defects
-
- Limited by long wavelength and small number of rays for reconstruction
 - Cracks are reported as cavities

Resistograph

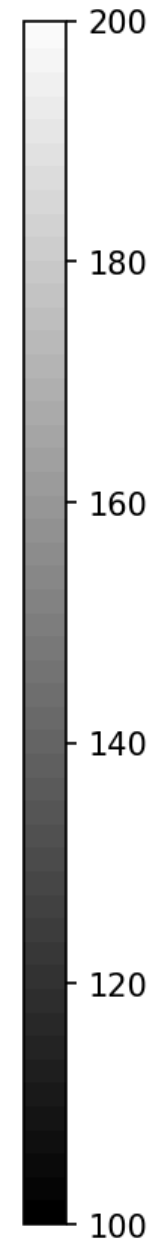
- Measures the power required for microdrilling at a fixed speed
- Provides **local** mechanical properties of the material
- Note short(!) valleys: the central cavity hypotheses is not accepted
- Projection of the data to the stem cross section would reveal details of the defect



Resistograph Data Visualization in 2D plane



5cm 10cm



Data in cross section geometry

- Transform resistograph data into 2D cross-section geometry
- Two types of visualization
 - curves
 - color scale
- Written as Python library
- Published on GitHub

Merge data

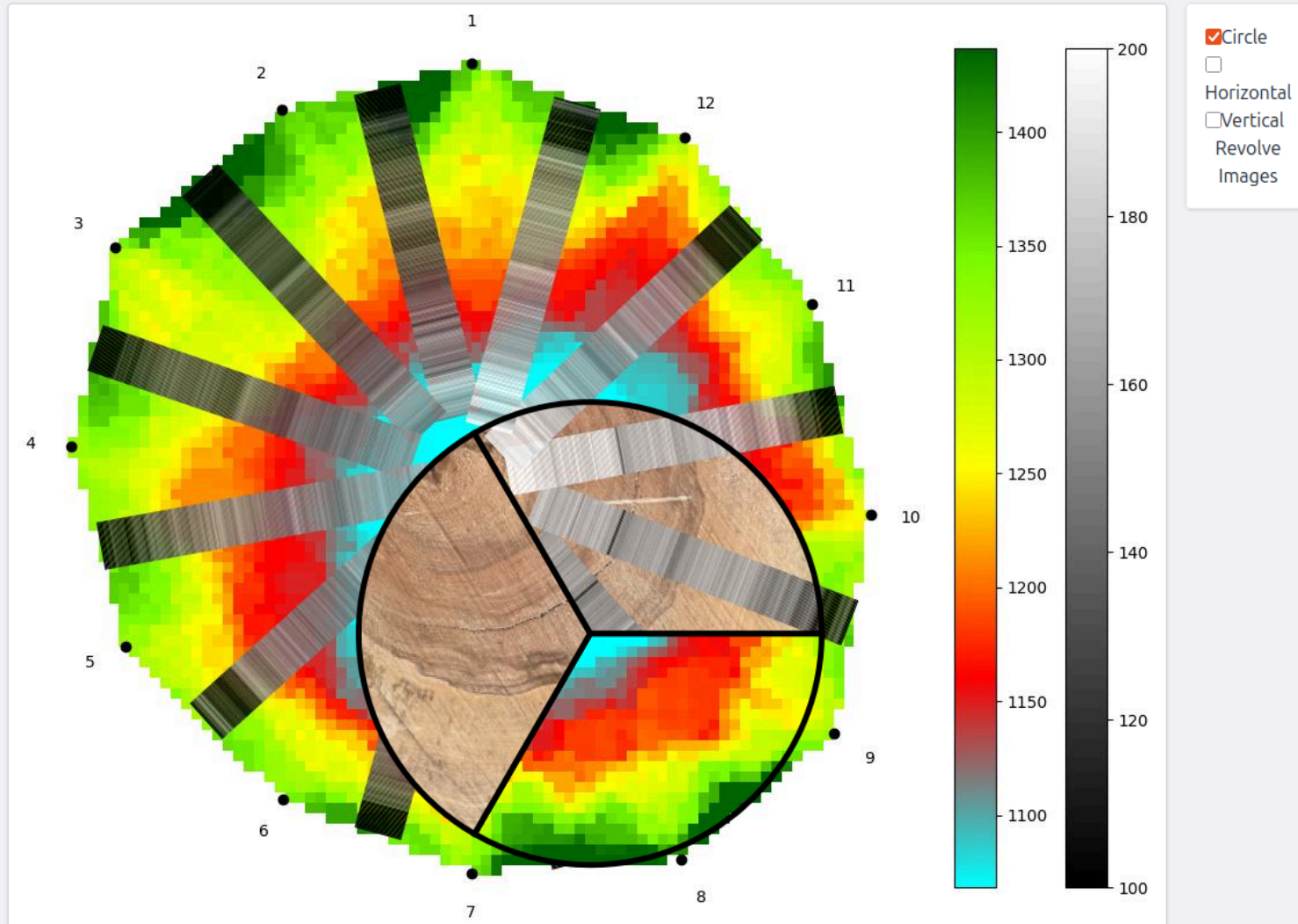
- Resistograph data in a tomogram
- Increases the accuracy of data interpretation
- The dark strips allow to localize the defect
- In our case the hypotheses have been confirmed by detailed inspection after felling the tree

When resistograph meets tomograph

The demo of overlays of four images. See [the repository](#) for the code.

- Tomogram
- Tomogram with resistograph data
- Section photo
- Section photo with resistograph data

You can move the mouse over the image to reveal the other layers or click the image to switch layers.



Python library

Advantages

- Python is widely used in scientific data processing
- Easy automation, scaling, modification, sharing, and reuse
- Simple [integration](#) with other tools

```

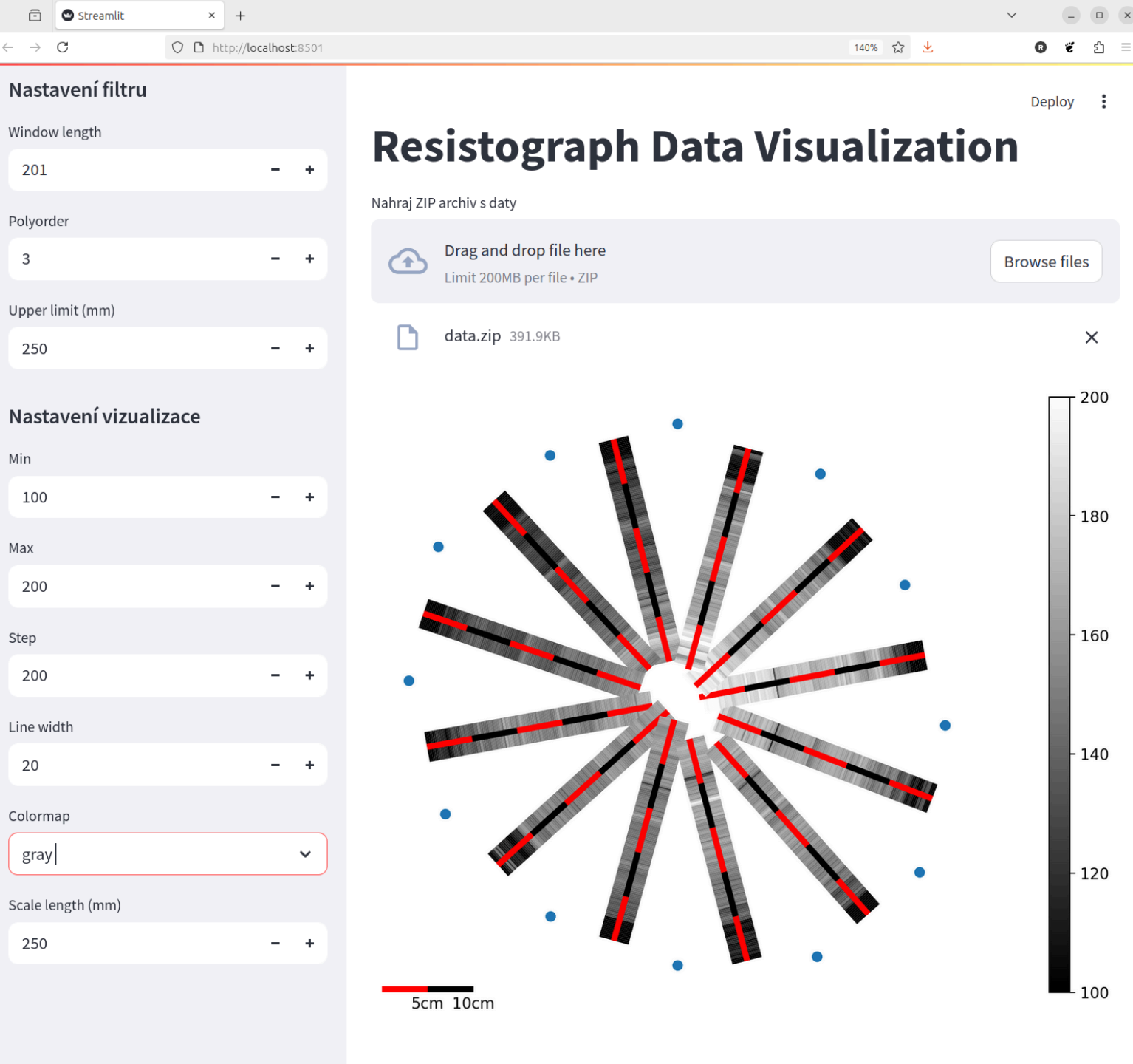
4 # See LICENSE file or https://creativecommons.org/licenses/by/4.0/
  Run Cell | Run Below | Debug Cell
5 #%%
6 """
7 This script visualizes resistograph data on a tomogram.
8 It processes resistograph data files and node coordinates to generate a plot
9 with resistograph data overlaid on a tomographic representation.
10
11 Configuration and validation are handled via Pydantic models.
12 """
  Run Cell | Run Above | Debug Cell
13 #%%
14 import pandas as pd
15 import numpy as np
16 import matplotlib.pyplot as plt
17 import glob
18 from scipy.signal import savgol filter
19 import logging
20 from matplotlib.collections import LineCollection
21 from matplotlib.transforms import Affine2D
22
23 # --- NEW: importy pro konfiguraci ---
24 from pydantic import BaseModel, Field, PositiveInt, DirectoryPath, model_validator
25 from typing import List, Optional
26
27 # Logging configuration
28 logging.basicConfig(level=logging.WARNING, format='%(levelname)s - %(message)s')
29
30 # --- NEW: Pydantic models for configuration ---
31 class FilterSettings(BaseModel):
32     window_length: PositiveInt = Field(201, description="Window length for Savitzky-Golay filter")
33     polyorder: int = Field(3, description="Polynomial order for filter")
34     upper_limit: int = Field(250, description="Maximum depth in mm")
35
36     @model_validator(mode="after")
37     def check_polyorder_vs_window(self):
38         if self.polyorder >= self.window_length:
39             raise ValueError("polyorder must be smaller than window_length")
40         return self
41
42
43 class PlotSettings(BaseModel):
44     min: int = Field(100, description="Minimum value for color normalization")
45     max: int = Field(200, description="Maximum value for color normalization")
46     step: int = Field(200, description="Step for downsampling")
47     linewidth: int = Field(20, description="Line width")
48     cmap: str = Field("gray", description="Matplotlib colormap")
49
50     @model_validator(mode="after")

```

Python library

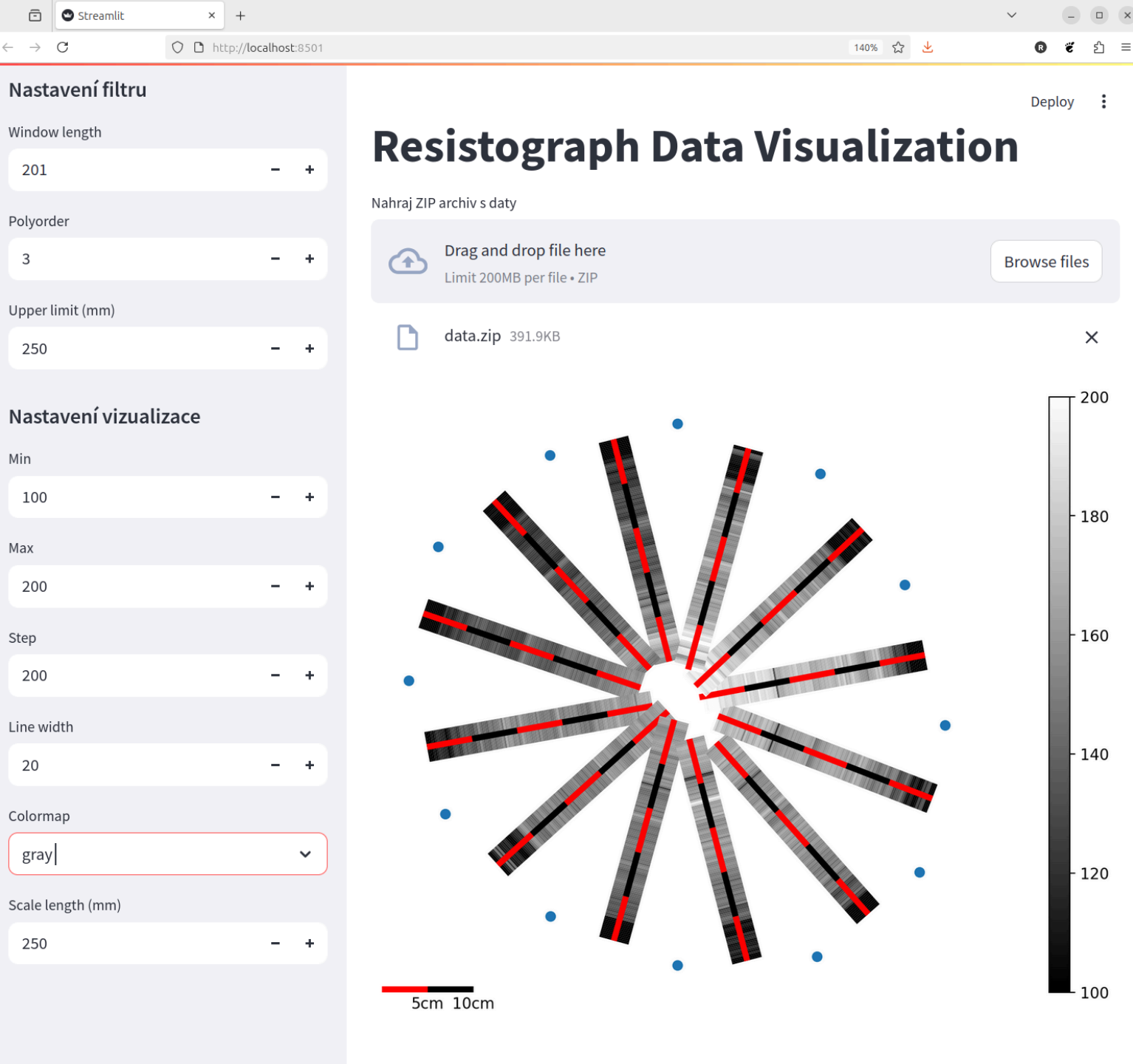
Limitations

- Needs installation of Python ecosystem
- Requires programming skills
- No graphical user interface



Streamlit

- Library for building interactive web apps
- GUI in web browser
- Widely used in industry and academia
- Requires minimal code



Vibe coding

- Code written by AI (LLM)
- ChatGPT 5 in August 2025
- Web app produced in two prompts

I have the following library. Write a streamlit program that allows you to upload a zipped directory with data and run commands corresponding to the main function on it. The output will be displayed.

OK. I want to be able to change the preset options in the left panel.


```

1  services:
    > Run Service
2  resisto:
3      network_mode: bridge
4      working_dir: /app/app
5      ports:
6      - 8501:8501
7      image: resisto:latest
8      build: .

```

Docker

- Packages app and dependencies into a single container
 - Ensures consistency across environments - ideal for **transparent and repeatable data processing**
 - Widely used in industry and academia
-
- In some fields, the "compute capsule" is submitted together with the manuscript (Code Ocean).

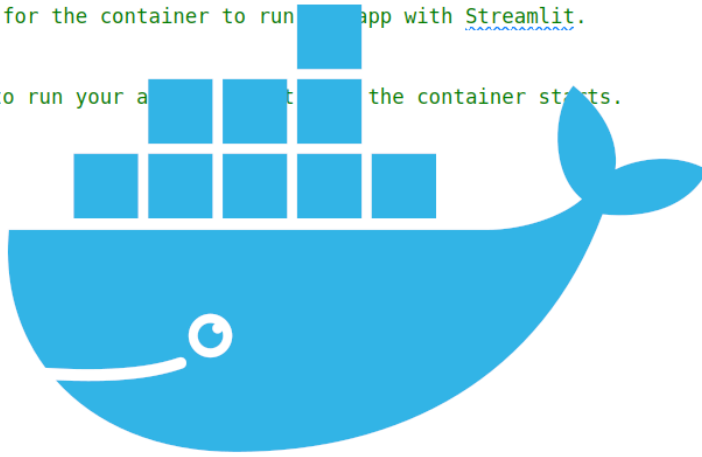
Dockerfile 1 X

Dockerfile > ...

```

1  # This sets up the container with Python 3.10 installed.
2  FROM python:3.10-slim (last pushed 3 weeks ago)
3
4  WORKDIR /app
5  COPY requirements.txt ./
6  RUN pip install --no-cache-dir -r requirements.txt
7
8  COPY . .
9
10 # This tells Docker to listen on port 80 at runtime. Port 80 is the standard port for HTTP.
11 EXPOSE 80
12
13 # This command creates a .streamlit directory in the home directory of the container.
14 RUN mkdir ~/.streamlit
15
16 # This copies your Streamlit configuration file into the .streamlit directory you just created.
17 RUN cp config.toml ~/.streamlit/config.toml
18
19 # This sets the default command for the container to run your app with Streamlit.
20 ENTRYPOINT ["streamlit", "run"]
21
22 # This command tells Streamlit to run your app when the container starts.
23 CMD ["app.py"]

```

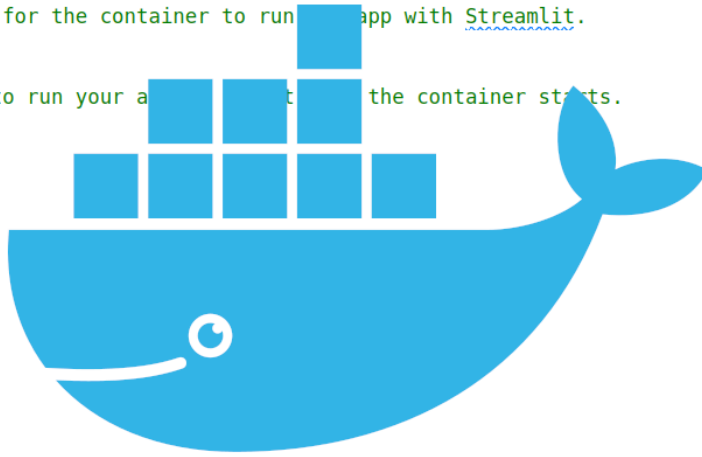


```
compose.yml > ...
  ▸ Run All Services
1  services:
  ▸ Run Service
2  resisto:
3    network_mode: bridge
4    working_dir: /app/app
5    ports:
6      - 8501:8501
7    image: resisto:latest
8    build: .
```

Run dockerized app

docker compose up

```
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- First run takes minutes, later runs take ms
- No Python install required
- No dependency issues
- Works on Win / Mac / Linux



Summary

- Resistograph and tomograph are complementary tools for tree inspection
- A Python library was developed to enhance data interpretation
- GUI is possible with Streamlit
- Coding can be done with AI support
- Installation can be simplified and repeated with Docker